


... in factory class definition ...

```
double slope, offset, exponent;
```

... in brun() method ...

```
map<string, double> twpars;  
loop->GetCalib("FDC/driftvelocity/timewalk_parameters", twpars);
```

```
slope      = twpars["slope"];  
offset     = twpars["offset"];  
exponent   = twpars["exponent"];
```



*Template method converts
values to doubles using
stringstream class*